

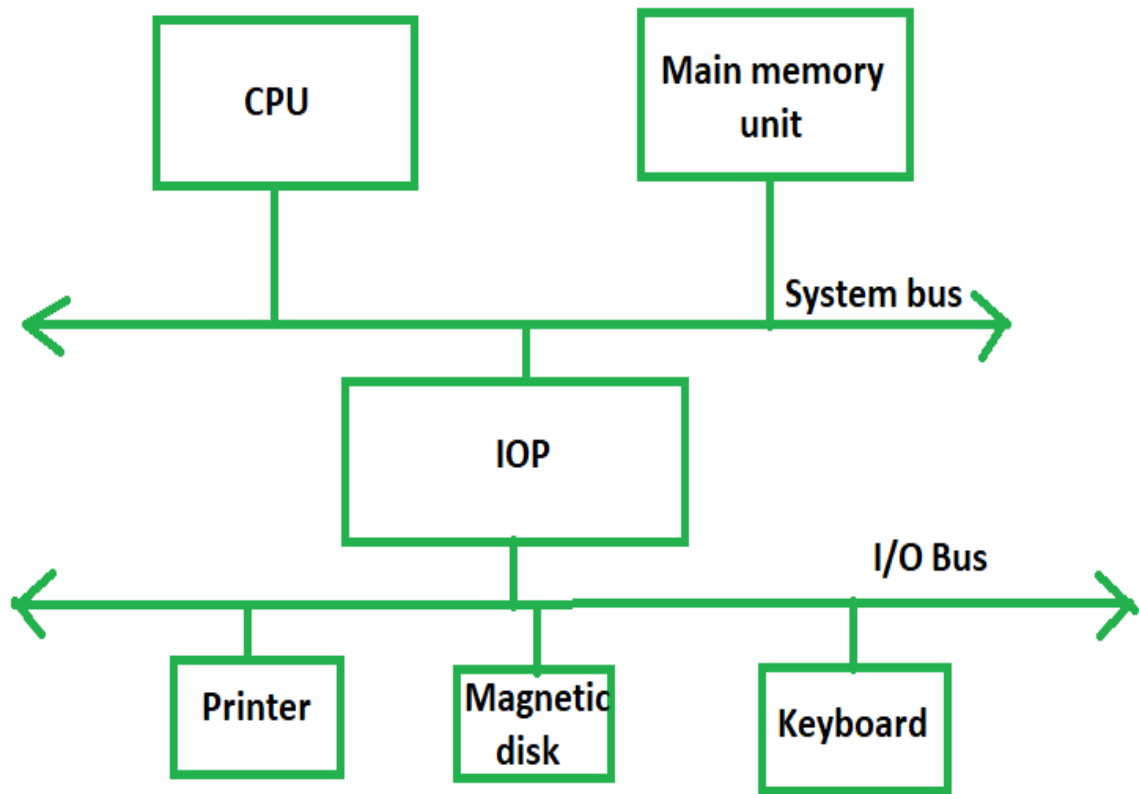
Input-output processor and Modes of Transfer

Introduction of Input-Output Processor

The **DMA mode** of data transfer reduces CPU's overhead in handling I/O operations. It also allows parallelism in CPU and I/O operations. Such parallelism is necessary to avoid wastage of valuable CPU time while handling I/O devices whose speeds are much slower as compared to CPU. The concept of DMA operation can be extended to relieve the CPU further from getting involved with the execution of I/O operations. This gives rise to the development of special purpose processor called **Input-Output Processor (IOP) or IO channel**.

The Input Output Processor (IOP) is just like a CPU that handles the details of I/O operations. It is more equipped with facilities than those are available in typical DMA controller. The IOP can fetch and execute its own instructions that are specifically designed to characterize I/O transfers. In addition to the I/O – related tasks, it can perform other processing tasks like arithmetic, logic, branching and code translation. The main memory unit takes the pivotal role. It communicates with processor by the means of DMA.

The block diagram –



Input-Output Processor

The Input Output Processor is a specialized processor which loads and stores data into memory along with the execution of I/O instructions. It acts as an interface between system and devices. It involves a sequence of events to executing I/O operations and then store the results into the memory.

Advantages –

- The I/O devices can directly access the main memory without the intervention by the processor in I/O processor based systems.
- It is used to address the problems that are arises in Direct memory access method.

Mode of Transfer:

The binary information that is received from an external device is usually stored in the memory unit. The information that is transferred from the CPU to the external device is originated from the memory unit. CPU merely processes the information but the source and target is always the memory unit. Data transfer between CPU and the I/O devices may be done in different modes.

Data transfer to and from the peripherals may be done in any of the three possible ways

1. Programmed I/O.
2. Interrupt- initiated I/O.
3. Direct memory access(DMA).

Now let's discuss each mode one by one.

1. **Programmed I/O:** It is due to the result of the I/O instructions that are written in the computer program. Each data item transfer is initiated by an instruction in the program. Usually the transfer is from a CPU register and memory. In this case it requires constant monitoring by the CPU of the peripheral devices.
Example of Programmed I/O: In this case, the I/O device does not have direct access to the memory unit. A transfer from I/O device to memory requires the execution of several instructions by the CPU, including an input instruction to transfer the data from device to the CPU and store instruction to transfer the data from CPU to memory. In programmed I/O, the CPU stays in the program loop until the I/O unit indicates that it is ready for data transfer. This is a time consuming process since it needlessly keeps the CPU busy. This situation can be avoided by using an interrupt facility. This is discussed below.
2. **Interrupt- initiated I/O:** Since in the above case we saw the CPU is kept busy unnecessarily. This situation can very well be avoided by using an interrupt driven method for data transfer. By using interrupt facility and special commands to inform the interface to issue an interrupt request signal whenever data is available from any device. In the meantime the CPU can proceed for any other program execution. The interface meanwhile keeps monitoring the device. Whenever it is determined that the device is ready for data transfer it initiates an interrupt request signal to the computer. Upon

detection of an external interrupt signal the CPU stops momentarily the task that it was already performing, branches to the service program to process the I/O transfer, and then return to the task it was originally performing.

Note: Both the methods programmed I/O and Interrupt-driven I/O require the active intervention of the processor to transfer data between memory and the I/O module, and any data transfer must transverse a path through the processor. Thus both these forms of I/O suffer from two inherent drawbacks.

- The I/O transfer rate is limited by the speed with which the processor can test and service a device.
 - The processor is tied up in managing an I/O transfer; a number of instructions must be executed for each I/O transfer.
3. **Direct Memory Access:** The data transfer between a fast storage media such as magnetic disk and memory unit is limited by the speed of the CPU. Thus we can allow the peripherals directly communicate with each other using the memory buses, removing the intervention of the CPU. This type of data transfer technique is known as DMA or direct memory access. During DMA the CPU is idle and it has no control over the memory buses. The DMA controller takes over the buses to manage the transfer directly between the I/O devices and the memory unit.

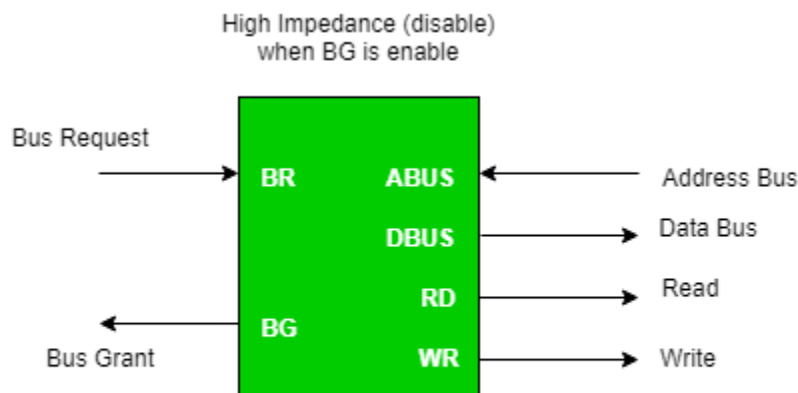


Figure - CPU Bus Signals for DMA Transfer

Bus Request : It is used by the DMA controller to request the CPU to relinquish the control of the buses.

Bus Grant : It is activated by the CPU to Inform the external DMA controller that the buses are in high impedance state and the requesting DMA can take control of the buses. Once the DMA has taken the control of the buses it transfers the data. This transfer can take place in many ways.

Types of DMA transfer using DMA controller:

Burst Transfer :

DMA returns the bus after complete data transfer. A register is used as a byte count,

being decremented for each byte transfer, and upon the byte count reaching zero, the DMAC will

release the bus. When the DMAC operates in burst mode, the CPU is halted for the duration of the data transfer.

Steps involved are:

1. Bus grant request time.
 2. Transfer the entire block of data at transfer rate of device because the device is usually slow than the speed at which the data can be transferred to CPU.
 3. Release the control of the bus back to CPU
- So, total time taken to transfer the N bytes
= Bus grant request time + (N) * (memory transfer rate) + Bus release control time.

Where,

$X \mu\text{sec} = \text{data transfer time or preparation time (words/block)}$

$Y \mu\text{sec} = \text{memory cycle time or cycle time or transfer time (words/block)}$

$\% \text{ CPU idle (Blocked)} = (Y/X+Y)*100$

$\% \text{ CPU Busy} = (X/X+Y)*100$

Cyclic Stealing :

An alternative method in which DMA controller transfers one word at a time after which it must return the control of the buses to the CPU. The CPU delays its operation only for one memory cycle to allow the direct memory I/O transfer to “steal” one memory cycle.

Steps Involved are:

4. Buffer the byte into the buffer
5. Inform the CPU that the device has 1 byte to transfer (i.e. bus grant request)
6. Transfer the byte (at system bus speed)
7. Release the control of the bus back to CPU.

Before moving on transfer next byte of data, device performs step 1 again so that bus isn't tied up and

the transfer won't depend upon the transfer rate of device.

So, for 1 byte of transfer of data, time taken by using cycle stealing mode (T).

= time required for bus grant + 1 bus cycle to transfer data + time required to release the bus, it will be

$N \times T$

In cycle stealing mode we always follow pipelining concept that when one byte is getting transferred then Device is parallel preparing the next byte. "The fraction of CPU time to the data transfer time" if asked then cycle stealing mode is used.

Where,

$X \mu\text{sec}$ = data transfer time or preparation time

(words/block)

$Y \mu\text{sec}$ = memory cycle time or cycle time or transfer

time (words/block)

% CPU idle (Blocked) = $(Y/X) \times 100$

% CPU busy = $(X/Y) \times 100$

Interleaved mode: In this technique, the DMA controller takes over the system bus when the microprocessor is not using it. An alternate half cycle i.e. half cycle DMA + half cycle processor.

Input/Output Processor

An input-output processor (IOP) is a processor with direct memory access capability. In this, the computer system is divided into a memory unit and number of processors.

Each IOP controls and manage the input-output tasks. The IOP is similar to CPU except that it handles only the details of I/O processing. The IOP can fetch and

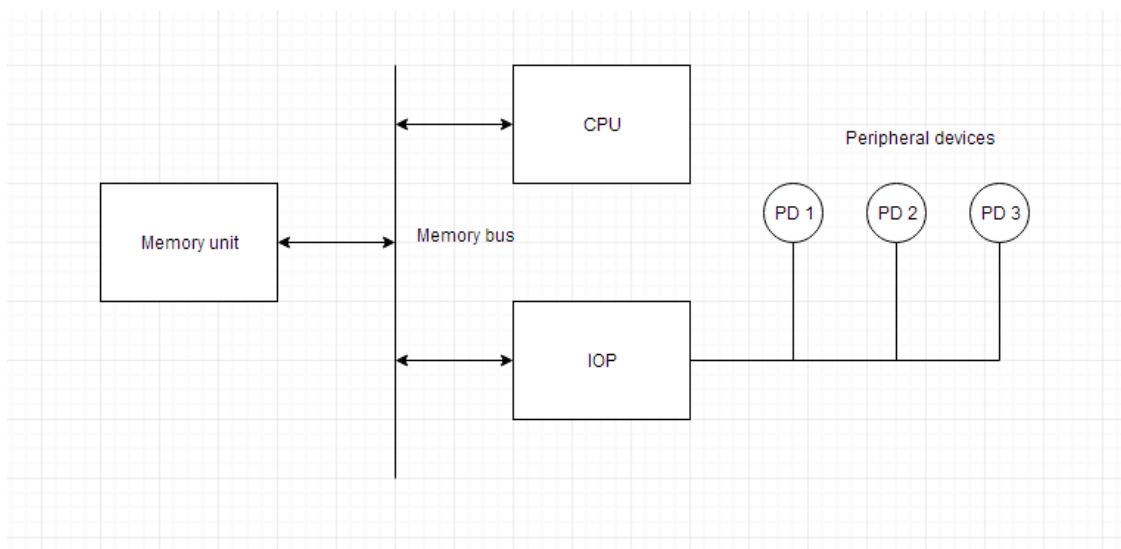
execute its own instructions. These IOP instructions are designed to manage I/O transfers only.

Block Diagram Of I/O Processor

Below is a block diagram of a computer along with various I/O Processors. The memory unit occupies the central position and can communicate with each processor.

The CPU processes the data required for solving the computational tasks. The IOP provides a path for transfer of data between peripherals and memory. The CPU assigns the task of initiating the I/O program.

The IOP operates independent from CPU and transfer data between peripherals and memory.



The communication between the IOP and the devices is similar to the program control method of transfer. And the communication with the memory is similar to the direct memory access method.

In large scale computers, each processor is independent of other processors and any processor can initiate the operation.

The CPU can act as master and the IOP act as slave processor. The CPU assigns the task of initiating operations but it is the IOP, who executes the instructions, and

not the CPU. CPU instructions provide operations to start an I/O transfer. The IOP asks for CPU through interrupt.

Instructions that are read from memory by an IOP are also called *commands* to distinguish them from instructions that are read by CPU. Commands are prepared by programmers and are stored in memory. Command words make the program for IOP. CPU informs the IOP where to find the commands in memory.